

# A general survey on STP

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or with the equivalent notation  $L = \delta_k [i_1 \ i_2 \ \dots \ i_n]$ .



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- $[k]$  denotes the integer set  $\{1, 2, \dots, k\}$ .
- $\mathbf{1}_k$  is the vector of size  $k$  with all unitary entries.

## Definition of STP (1)

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$$A \otimes B := \begin{bmatrix} a_{11}B & a_{12}B & \dots & a_{1c_A}B \\ a_{21}B & a_{22}B & \dots & a_{2c_A}B \\ \vdots & \vdots & \ddots & \vdots \\ a_{r_A1}B & a_{r_A2}B & \dots & a_{r_Ac_A}B \end{bmatrix}$$

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The size of  $A \otimes B$  is  $(r_A r_B) \times (c_A c_B)$ .



## Definition of STP (2)

- The **semi-tensor product**  $\ltimes$  between matrices  $A = [a_{ij}] \in \mathbb{R}_{r_A \times c_A}$  and  $B = [b_{ij}] \in \mathbb{R}_{r_B \times c_B}$  is defined as

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The size of  $A \ltimes B$  is  $(r_A T / c_A) \times (c_B T / r_B)$ .

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Example: Suppose

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 5 \\ 6 \\ 7 \end{bmatrix}.$$

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Then  $c_A = 2$ ,  $r_B = 3$  and  $T = 6$ , so that

$$A \ltimes B = (A \otimes I_3)(B \otimes I_2) = \begin{bmatrix} 1 & 0 & 0 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 & 0 & 2 \\ 3 & 0 & 0 & 4 & 0 & 0 \\ 0 & 3 & 0 & 0 & 4 & 0 \\ 0 & 0 & 3 & 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & 5 \\ 6 & 0 \\ 0 & 6 \\ 7 & 0 \\ 0 & 7 \end{bmatrix}$$

# Bijjective correspondence between Boolean vectors and logical vectors (1)

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so that

$$X = 1 \longleftrightarrow x = L(X) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \delta_2^1, \quad X = 0 \longleftrightarrow x = L(X) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \delta_2^2.$$

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- It extends to a **bijjective correspondence** between  $\mathcal{B}^n$  and  $\Delta_{2^n}$  through:

$$X = [X_1 \quad X_2 \quad \dots \quad X_n]^\top \longleftrightarrow x = L(X_1) \bowtie L(X_2) \bowtie \dots \bowtie L(X_n).$$

# Bijjective correspondence between Boolean vectors and logical vectors (2)

Example:

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In general,

$$X = \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \longleftrightarrow x = L(X) = \begin{bmatrix} X_1 X_2 X_3 \\ X_1 X_2 \bar{X}_3 \\ X_1 \bar{X}_2 X_3 \\ X_1 \bar{X}_2 \bar{X}_3 \\ \bar{X}_1 X_2 X_3 \\ \bar{X}_1 X_2 \bar{X}_3 \\ \bar{X}_1 \bar{X}_2 X_3 \\ \bar{X}_1 \bar{X}_2 \bar{X}_3 \end{bmatrix}.$$

# Special matrices

- Given any two vectors  $X \in \Delta_n$  and  $Y \in \Delta_m$ , the **swap matrix**  $W_{[n,m]}$  is the (uniquely determined) permutation matrix such that

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- Given any vector  $X \in \Delta_n$ , the **power reducing matrix**  $\Phi_n$  is the (uniquely determined) matrix such that

$$X \ltimes X = \Phi_n X.$$

# Boolean networks

A **Boolean Network** (BN) is described by the following equations

$$\begin{aligned} X(t+1) &= f(X(t)), \\ Y(t) &= h(X(t)), \quad t \in \mathbb{Z}_+, \end{aligned} \tag{1}$$



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$$\begin{aligned} f &: \mathcal{B}^n \rightarrow \mathcal{B}^n, \\ h &: \mathcal{B}^n \rightarrow \mathcal{B}^p. \end{aligned}$$

# Boolean Control Networks

A **Boolean control network** (BCN) is described by the following equations

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# BNs and BCNs: from logic to algebraic representations (1)

Given any logical map

$$Z = g(X),$$

If we represent the Boolean vectors  $X$  and  $Z$  by means of their “canonical equivalent”,  $x$  and  $z$ , then we can always find a logical matrix  $M_g$ , called **structure matrix**, such that

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Consequently, every BN (1) can be described as

$$\begin{aligned} \mathbf{x}(t+1) &= L \ltimes \mathbf{x}(t), & t \in \mathbb{Z}_+, \\ \mathbf{y}(t) &= H \mathbf{x}(t) \end{aligned} \tag{3}$$

where  $L \in \mathcal{L}_{2^n \times 2^n}$  and  $H \in \mathcal{L}_{2^p \times 2^n}$ .

# BNs and BCNs: from logic to algebraic representations (2)

Similarly, every BCN (2) can be described as

$$\begin{aligned}\mathbf{x}(t+1) &= L \ltimes \mathbf{u}(t) \ltimes \mathbf{x}(t), & t \in \mathbb{Z}_+, \\ \mathbf{y}(t) &= H\mathbf{x}(t)\end{aligned}\tag{4}$$

where  $L \in \mathcal{L}_{2^n \times 2^{(n+m)}}$  and  $H \in \mathcal{L}_{2^p \times 2^n}$ .

# Thanks for your attention!

Questions?